

## Function Description Incubator 8000 IC / SC / NC

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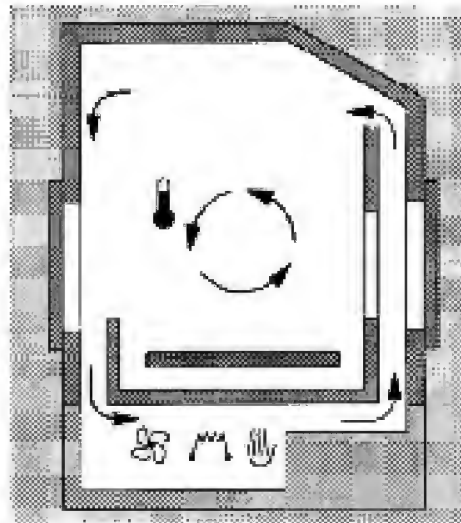
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## 1 General

### 1.1 Description of the Incubator 8000 IC / SC / NC

A special airflow system has been developed for the Incubator 8000 series. This system routes heated air between the double walls on the entire front (hinged front door), over the roof of the canopy and then draws it down again between the double walls at the rear by means of an extraction system. Thus the baby lies in an area with very low airflow so that heat loss by convection is reduced. For the Incubator 8000 SC / NC the double walls at the sides and at the rear are an option.



The all-round double wall design of the Incubator 8000 series canopy also reduces the loss of body heat by radiation. When the hinged front door and the hand port doors are open, there is still an effective hot air curtain which prevents appreciable cooling inside the canopy.

A new type of mattress gives very low heat loss by conduction through the bed, resulting in a high level of comfort for the baby. It is made of a particularly soft foam plastic, smoothly encased in film to provide an absolutely hygienic seal.

The incubator is equipped with easy-moving, swivelling castors which permit easy movement around the hospital. Two of the castors can be locked. There are rails, which can also be used as handles, on the sides for holding ancillary equipment.

The sensor housing which is located near the baby's head responds very rapidly to changes in the environment inside the incubator and contributes to a very sensitive control system. The housing contains the air temperature sensor, the optional oxygen sensor and the optional relative humidity sensor. It also contains the connection point for the skin temperature sensor on Incubator 8000 IC units without ThermoMonitoring.

At the Incubator 8000 SC / NC an air temperature sensor located near the baby's head is attached at the rear of the canopy, the connection point for the skin temperature sensor is located at the back of the Incubator next to the mains input on units without Thermomonitoring.

The optional oxygen control module on Incubator 8000 IC units permits the required oxygen concentration within the canopy to be pre-selected and controlled automatically. If the actual value deviates from the set value, warning signals are given. The control system permits a set oxygen concentration to be achieved within a very short time (40 % in 1.5 minutes and 60 % in < 7 minutes). This permits rapid action in emergencies and rapid return to a selected oxygen concentration after opening the hinged front door or the hand ports.

The humidity control of the Incubator 8000 IC permits a required humidity value to be pre-selected and maintained. The water required for this is supplied from sterile water bottles.

The humidity supply of the Incubator 8000 SC / NC humidity control can be adjusted in 10 steps.

Evaporation of the water guarantees completely hygienic air humidification.

In accordance with hygienic requirements, all parts of the Incubator which come into contact with the gas breathed by the baby can be removed from the basic unit.

The electrically-operated height adjustment mechanism permits an optimum working height to be set for both tall and small nurses. In addition, the Incubator can be lowered so that the nurse can carry out lengthy procedures whilst sitting down, and there is also adequate legroom beneath it.

The hand port openings have been designed to provide better access for the arms of the nursing staff than round openings do, yet have a smaller opening cross-section, thus reducing heat loss.

The incubator is controlled by a microprocessor. The Incubator carries out a general self-test when it is switched on and automatically every 10 minutes thereafter. This test checks the various assemblies in the incubator which are crucial to safety by operating them briefly. The operator is automatically requested to recalibrate the oxygen sensors after switching on the O<sub>2</sub> control system and, thereafter, after every 24 hours of operation. Measured value deviations or system failures are indicated visually and audibly. The heating system and valve are automatically switched off if operating conditions are outside permitted limits.

The control systems for air temperature, skin temperature and humidity are PI- or PID-controls and give optimum control.

An additional built-in air-cooler produces rapid cooling as soon as the actual value of the air temperature is a few tenths of a degree above the set value.

## 1.2 Safety Features

A self-test is conducted when the incubator is switched on. This involves a test of all memories in the microprocessor control system and a check to establish whether the various program segments are running correctly.

The function of actuators, acknowledgement signals, displays and indications is checked by switching them on and off. For example, the functioning of the fan is checked not by establishing whether power is reaching the electric motor, but rather by measuring the speed of rotation directly on the fan. The wiring to peripheral devices is provided in duplicate.

This complete test is also repeated every 10 minutes during operation.

All options, whether they are activated or not, are tested. An error message is thus indicated for a faulty module even if it is switched off. This ensures that the operator is always fully aware of the actual condition of the incubator.

When the incubator is switched on again, or when a module is switched on, the relevant required value is set to "starting value". The set value display then flashes requesting confirmation or modification of this value. The actual value indication is displayed alternately with the prompt "SET" (not humidity Inc. 8000 SC / NC).

## 1.3 Alarms

The incubator has a graduated system of alarm signals. Faults which occur are signalled in order of importance. If a non-essential option fails, it does not mean that the incubator has to discontinue any functions which are of vital importance. The set value deviation and water shortage alarms are signalled by an intermittent warning tone which can be suppressed for 10 minutes. Faults which entail greater potential danger are signalled by a continuous tone which cannot be silenced. In addition, the relevant warning LEDs flash to enable the operator to locate the fault rapidly. The alarm signals are described in detail below.

### 1.3.1 Alarm for set value deviations and water shortage

Deviations outside the set limits for oxygen concentration ( $> 5\%$  by Vol. O<sub>2</sub>), skin temperature ( $> 0.5\text{ °C}$  with software version 10.n or 20.n and  $> 1.0\text{ °C}$  with software version 11.n and 21.n on us units only) and air temperature ( $> 1.5\text{ °C}$ ), in addition to over-temperature ( $> 38\text{ °C}$  or  $> 39.9\text{ °C}$ ) and water shortage result in the following alarm signals:

- The actual value display of the relevant control module flashes.
- The specific alarm LED flashes.
- Intermittent alarm tone sounds (can be suppressed for 10 min.).
- The central alarm LED flashes (if available).

The alarm tone for set value difference - 1.5 °C air temperature - is suppressed automatically for 30 minutes when the incubator is switched on to avoid a continuous alarm signal sounding during the warming-up phase.

The "Reset" warning button for over-temperature has to be reset by the operator to ensure full awareness of the error. All other alarms are reset automatically when the relevant conditions have returned to normal.

If an alarm has been suppressed, the red alarm LED, which had previously flashed, stays alight but is constant, and a yellow LED indicator above the switch-off button indicates the switched-off mode. If another alarm occurs when alarms are suppressed, the audible alarm is re-activated immediately. Depending on the type of fault, this later alarm can be suppressed again. The period for automatic reactivation of the first alarm tone is then prolonged by the time interval between the two alarms.

### **1.3.2 Sensor alarms and fan failure alarm**

Faults in the sensors for oxygen, skin temperature, humidity, air temperature and failure of the fan produce the following alarm signals:

- Three dashes ("---") flash on the relevant actual value display.
- The actual air temperature value flashes in the event of fan failure.
- The specific alarm LED flashes. 0 Continuous alarm tone (non-suppressible)
- The central alarm LED flashes (if available).

Where there have been sensor warnings for oxygen concentration or relative humidity and the relevant module has been switched off, the incubator can continue to operate with the other functions. The same applies when there is a skin temperature control alarm, though, in this case, the faulty sensor must be removed.

### **1.3.3 Module faults**

Alarms for faults in the control modules for oxygen concentration, skin temperature and relative humidity produce the following alarm signals:

- The letters "Err" (= Error) appear on the relevant actual value display, flashing if the module is switched on and not flashing if the module is switched off.
- The red "Inop" LED is lit when the module is switched on.
- Continuous alarm tone (non-suppressible) if the module is switched on.

The functions of the other modules which are operating correctly are retained. The operator can carry on using the incubator after the faulty module has been switched off.

### **1.3.4 Total shutdown**

Faults in the central microprocessor control system and in the air temperature control module result in complete shutdown of the incubator. The following alarm signals are then given:

- Red "inop" LED is lit.
- Continuous alarm tone (non-suppressible).

Individual checks should be carried out to determine whether the fault appeared only temporarily. If the incubator shows the "Inop" signal after it is switched on again, it is inoperative. It must not be used and must be clearly marked faulty.

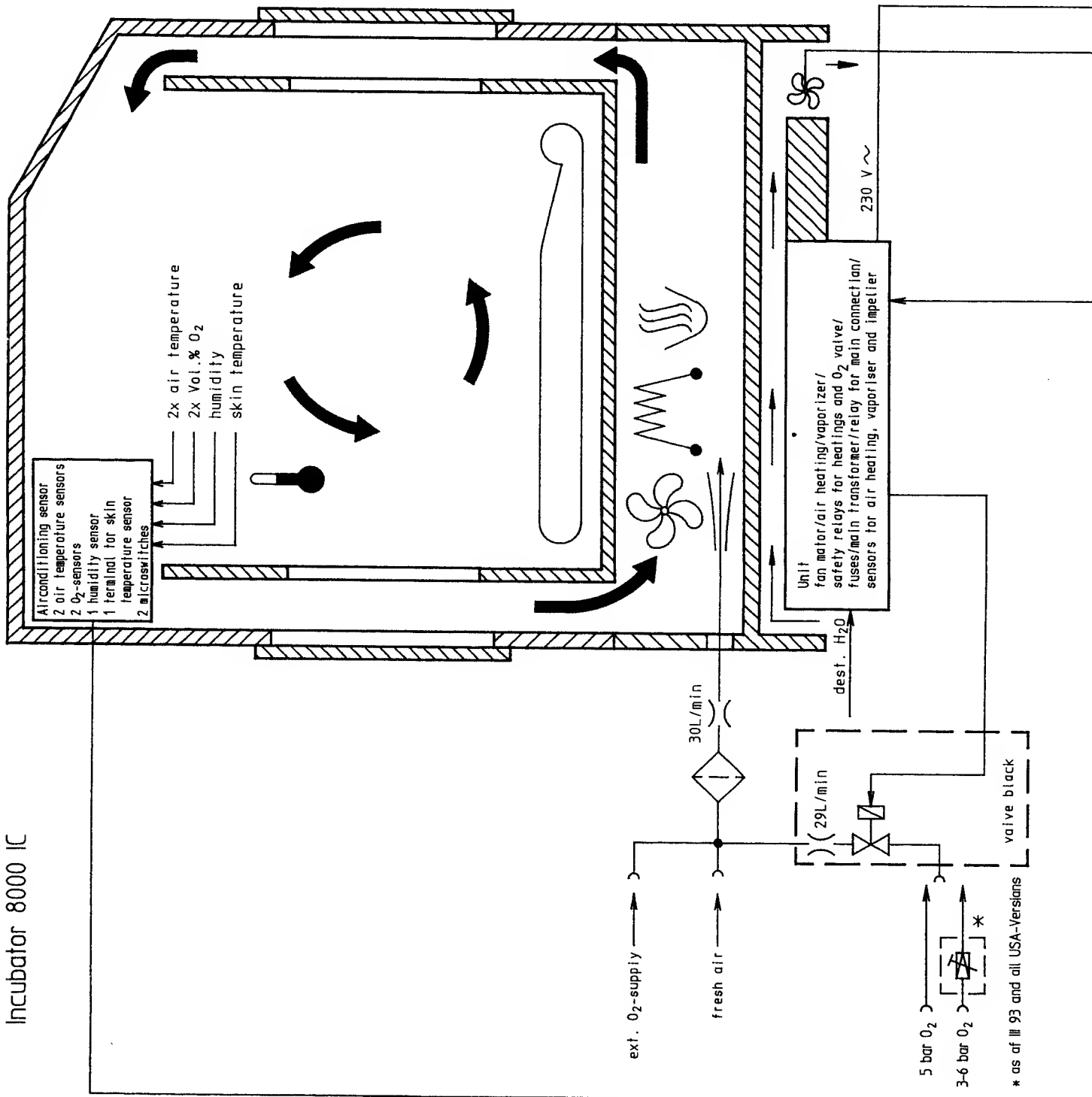
## **2 Functional description of Incubator 8000 IC / SC / NC**

### **2.1 Description of component block diagram**

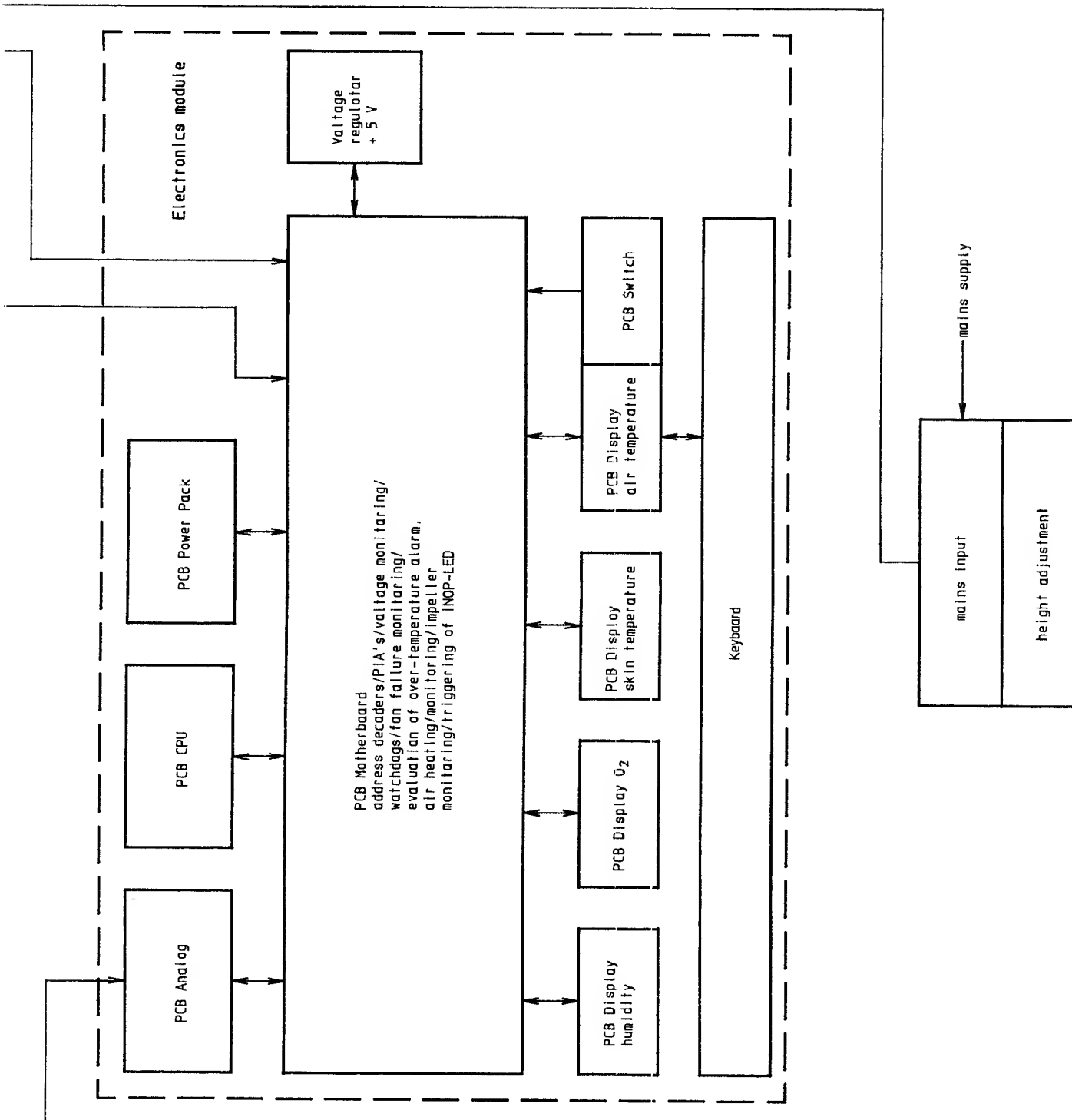
- Component block diagram 8000 IC
- Component block diagram 8000 SC / NC
- Fresh air intake and O<sub>2</sub>-supply
- Unit with air heating, fan and humidifier
- Electronics module
- Climate sensor (Inc. 8000 IC only)
- Air temperature sensor (Inc. 8000 SC / NC)
- Height adjustment

#### **2.1.1 Component block diagram 8000 IC**

# Incubator 8000 IC



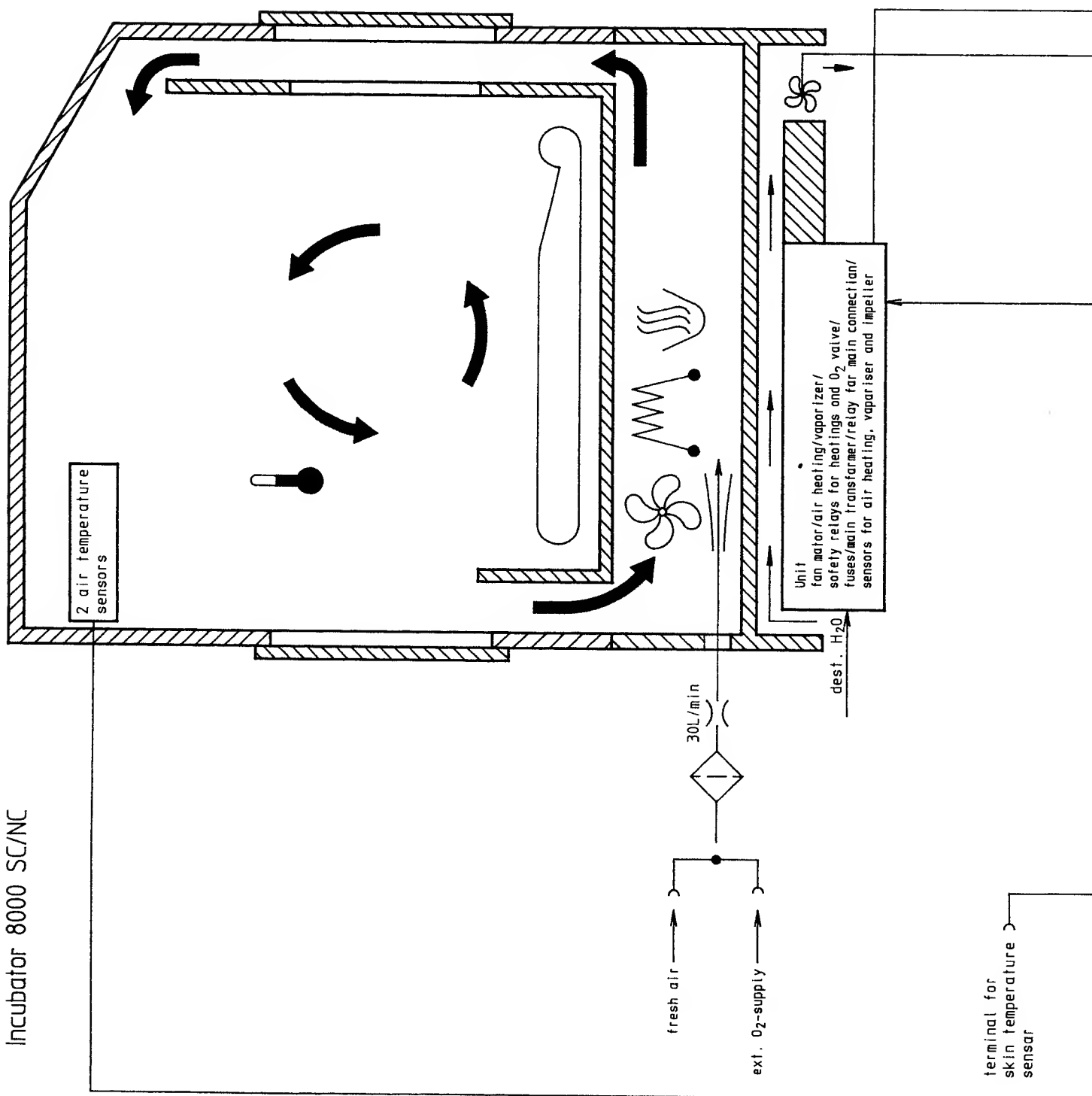


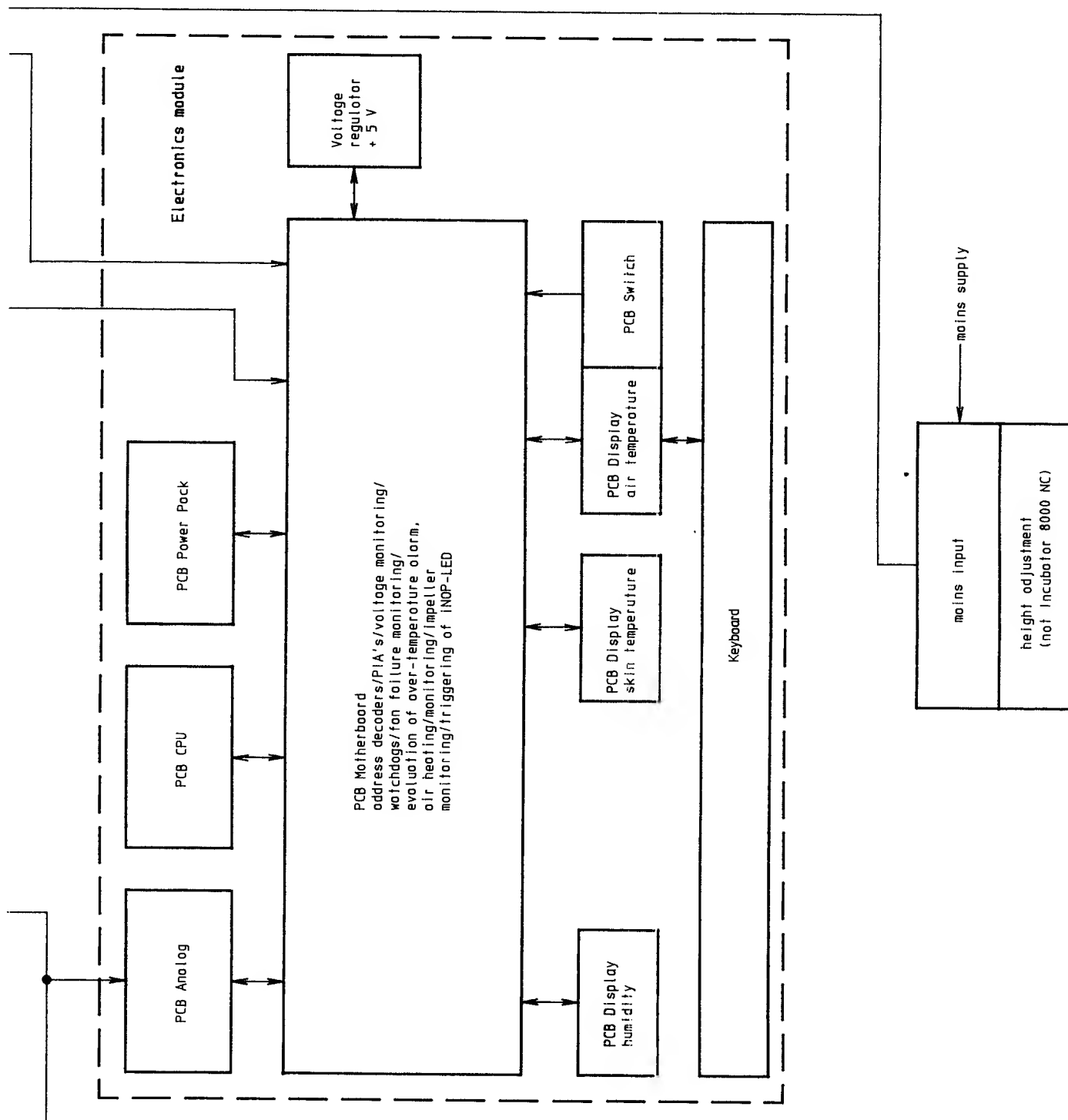


Components block diagram Incubator 8000 IC

## **2.1.2 Component block diagram 8000 SC / NC**

# Incubator 8000 SC/NC





Components block diagram Incubator 8000 SC/NC  
Page3

## **2.1.3 Fresh air intake and O2 supply**

### **2.1.3.1 Fresh air intake**

Through a fresh air filter 84 02 926 at the back of the Incubator 30 L/min fresh air are taken in by dosing via the running impeller.

### **2.1.3.2 O2 supply**

Incubator 8000 IC:

There are two possibilities for O2 supply in Incubator 8000 IC:

- a. External O2-supply
- b. Oxygen control

Incubator 8000 SC / NC:

With Incubator 8000 SC / NC only external O2-supply (a.) is possible.

#### **a. external O2 supply**

Via a socket oxygen can be supplied to the Incubator through a flowmeter. According to specification the oxygen concentration has to be monitored with an additional oxygen measuring instrument with upper and lower alarm limit.

#### **b. oxygen control**

An automatic control can be carried out with the integrated O2 concentration control. According to set value deviation one valve with 29 L/min is opened by the electronic control. According to specification the oxygen is supplied via the fresh air filter to the patient room.

## **2.1.4 Heating unit**

The following function blocks are on the unit:

- fan motor
- air heating with over-temperature fusing
- humidifier with over-temperature fusing
- mains transformer
- auxiliary mains transformer for mains connection
- semiconductor relay for air heating and humidifier
- safety relay for heatings and O2 valves
- Sensor for monitoring of:
  - the air heating (I/U converter)
  - the vaporizer (temperature for water shortage alarm)
  - the impeller (fan)
- fuses for the mains input and the internal supply voltages

## 2.1.5 Electronics module

The electronics module comprises the following function blocks:

- keyboard
- PCB Display Air Temperature:
  - a. triggering of display elements for air temperature control
  - b. read-out of keyboard
- PCB Display Options and PCB Display Humidity/Skin Temperature:  
triggering of the individual display elements of the options
- PCB CPU:
  - a. processor 6802
  - b. EPROM
  - c. RAM with internal battery for data backup
  - d. timer
  - e. watchdog
- PCB Analog
  - a. reading in of measured values of climate sensor housing (Inc. 8000 IC) or of air temperature sensor (Inc. 8000 SC / NC)
  - b. reading in of climate sensor housing position (Inc. 8000 IC)
  - c. processor-dependent monitoring circuit for over-temperature and existence of oxygen sensors
  - d. processor-dependent monitoring circuit for presence of oxygen sensors (Inc. 8000 IC)
- PCB Power Pack
  - a. Rectification of supply voltage +15 V and -15 V
  - b. Rectification and control of supply voltage +5 V. The voltage regulator is positioned on the right hand side panel of the electronics module.
  - c. Charaino circuit for battery of the mains failure-alarm.
  - d. Trigger circuit for horn and mains failure LED
  - e. Horn
- Motherboard
  - a. Address decoder for peripherals
  - b. PIAs for triggering of peripherals
  - c. Evaluation of over-temperature alarm
  - d. Fan failure monitoring
  - e. Watchdogs
  - f. Voltage monitoring
  - g. Evaluation of air heating monitoring
  - h. Evaluation of impeller monitoring

- i. Evaluation of valve monitoring
- j. Triggering of INOP-LED
- k. Triggering of additional fan

### **2.1.6 Climate sensor housing (Inc. 8000 IC)**

This sensor detects the climatic conditions inside the incubator. For calibration of the O<sub>2</sub> measurement function the sensor can be swung out of the incubator interior.

Function blocks:

- 2 air temperature sensors
- 2 O<sub>2</sub> sensors
- Terminal for skin temperature sensor (units with software version 20.n only)
- Humidity sensor with evaluation electronics
- 2 micro switches to determine sensor position

### **2.1.7 Air temperature sensor (Inc. 8000 SC / NC)**

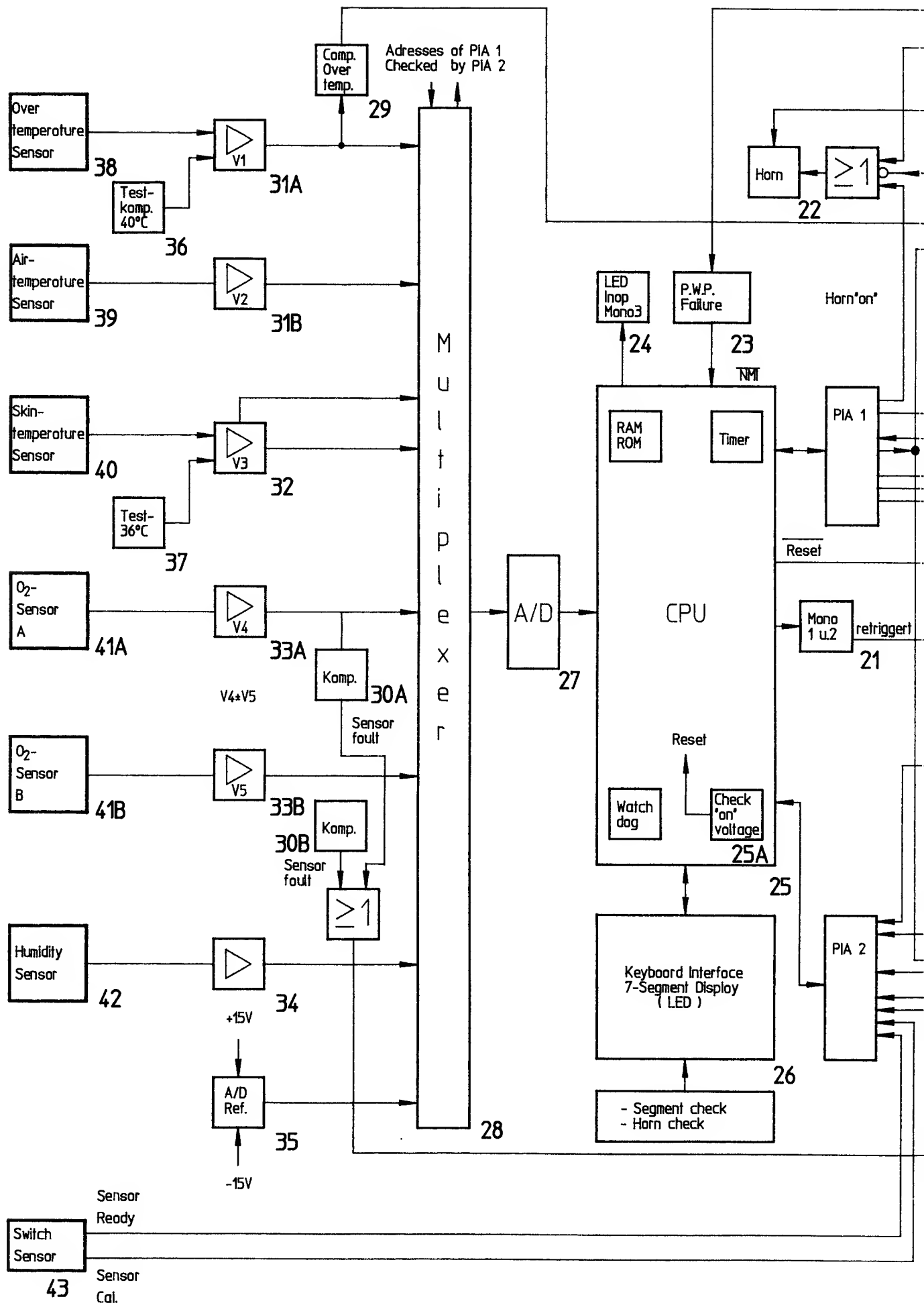
For measurement of the air temperature two identical sensors are enclosed in one housing.

### **2.1.8 Height adjustment**

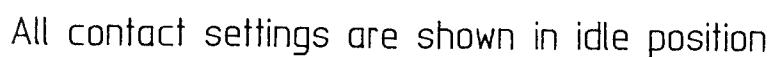
The height is adjusted via an Electro-motor with spindle. The pedestal is triggered via a foot-operated switch. The Electro-motor is equipped with an automatically resettable over-temperature switch.

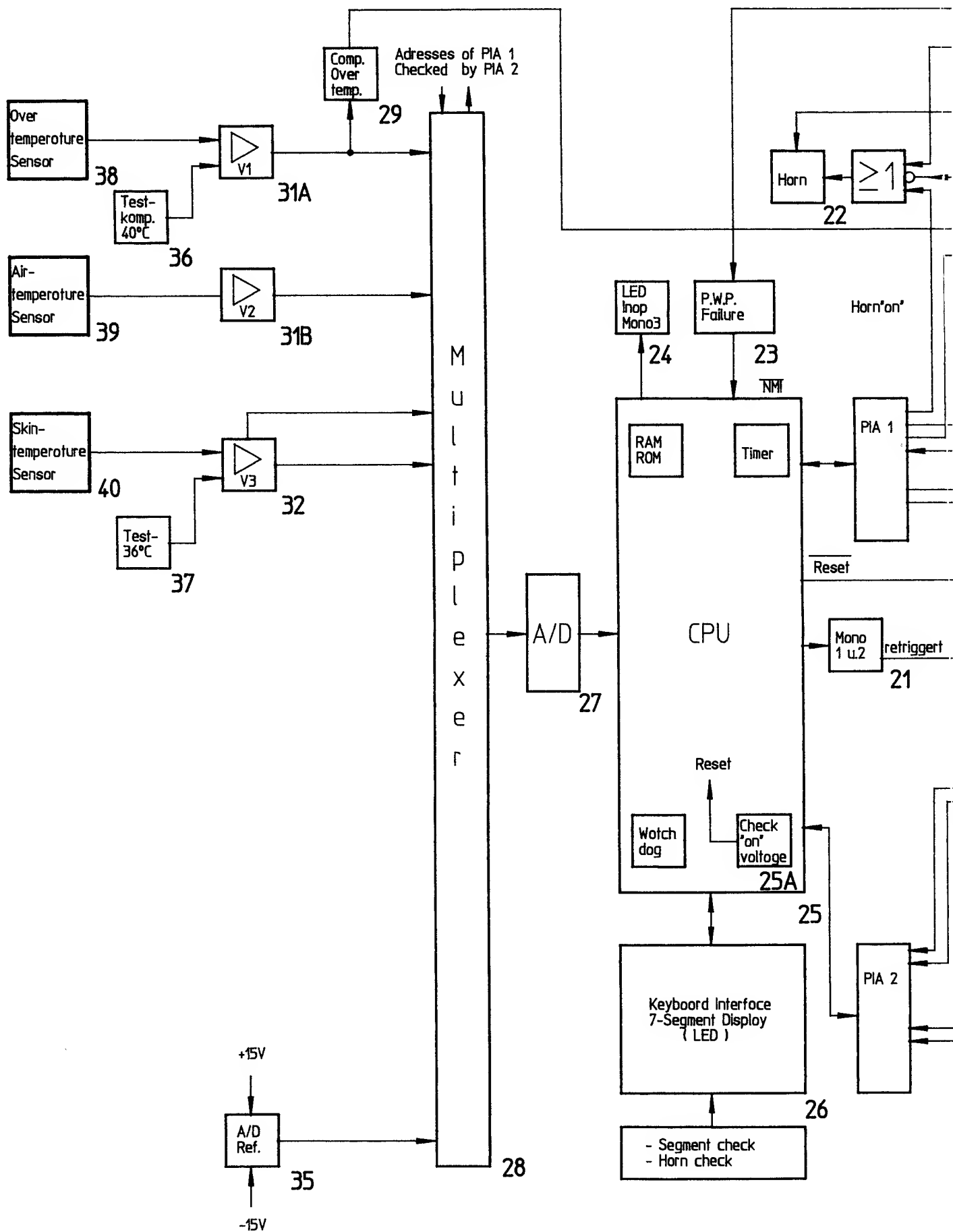
## **2.2. Description of block diagram of electronic functioning**

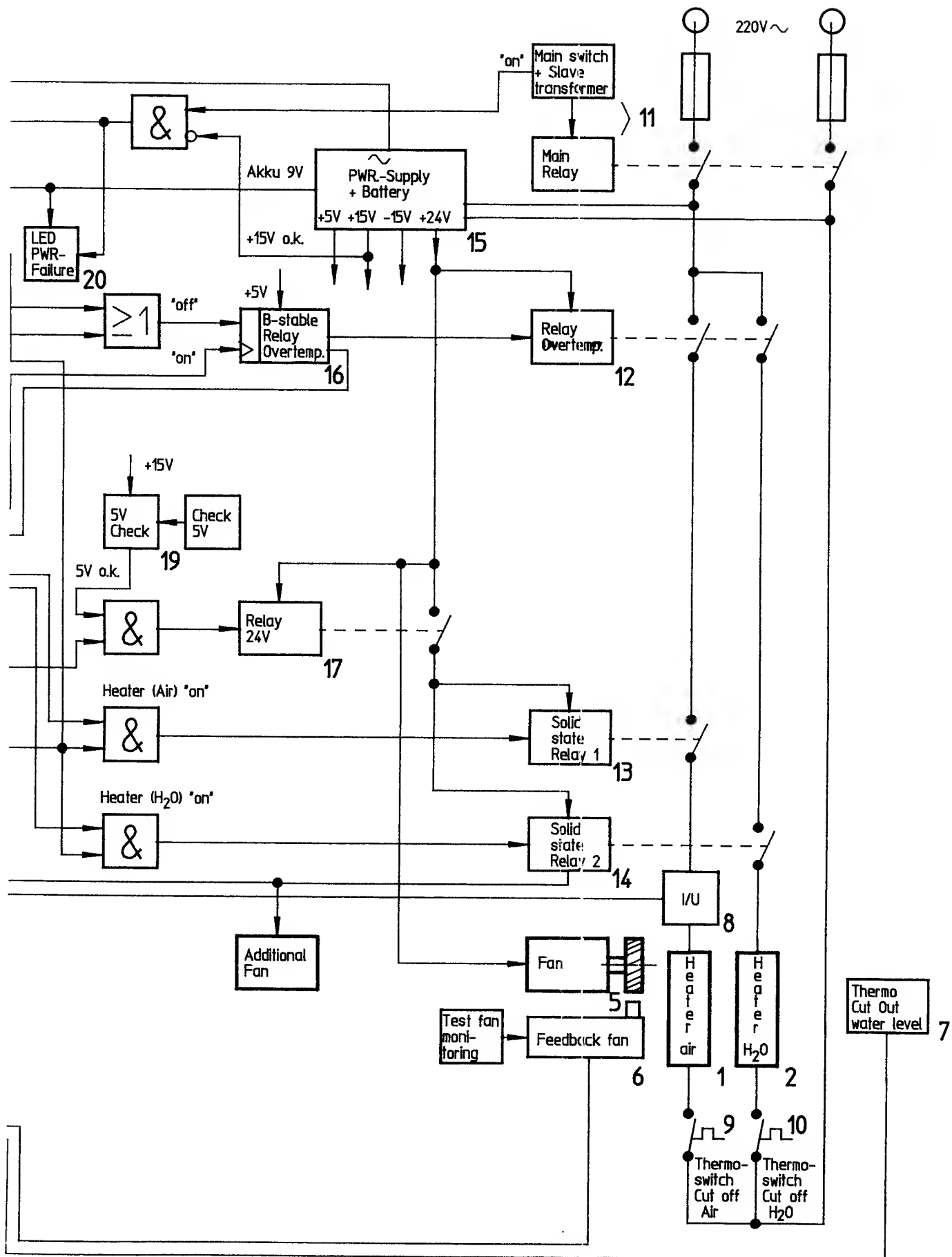
### **2.2.1 Incubator 8000 IC / SC / NC block diagrams**











All contact settings are shown in idle position

Block diagram  
Incubator 8000 SC/NC

'ds-6141.221aE/09.05.94/ab

## **2.2.2 Detailed description of block diagram**

The numbers in brackets refer to the position in the block diagram.

### **2.2.2.1 Air temperature sensor (39)**

The air temperature sensor is part of the feedback loop of an operational amplifier (31B). This operational amplifier produces an output voltage proportional to the air temperature. A second amplifier stage modifies the voltage to the input voltage range of the ADC. Resolution: 0.0 °C to 60.0 °C = 0.0 to 5.0 V.

### **2.2.2.2 Over-temperature sensor (38)**

The over-temperature sensor is mechanically integrated with the air temperature sensor in one housing. This allows a redundant measurement for the air temperature. The amplification factor and thus the output signal differs from the output signal of the air temperature sensor. The air and over-temperature sensor are checked crosswise by software. In case of a temperature difference of more than 0.5 °C a sensor alarm is produced. The over-temperature sensor is placed in the feedback loop of the operational amplifier (31A). A second amplifier stage modifies the voltage to the input voltage range of the ADC. Resolution: 0.0 to 50.0 °C = 0.0 to 5.0 V.

### **2.2.2.3 Over-temperature comparator (29)**

The output voltage of the over-temperature sensor circuit is additionally monitored by a comparator. The trigger level of this comparator is set to 40.0 °C. If the over-temperature sensor output voltage reaches this limit independent and unaffected by the microprocessor this comparator switches off the heater and sets the incubator into the safe operation mode. The over-temperature condition is stored and latched by a bipolar relay (16). After the temperature has fallen and the over-temperature sensor circuit is reset by the operator with a dedicated reset button, normal operation of the temperature control system is continued.

### **2.2.2.4 Testing of over-temperature comparator (36)**

Every 10 minutes the over-temperature sensor circuit (comparator) is tested by the microprocessor. On the Analog PCB the relay (K2) or by FET transistors on newer devices as of 1996 substitutes for a short time the over-temperature sensor with a fixed resistor simulating a temperature higher than 40.0 °C.

### **2.2.2.5 Skin temperature sensor (40)**

The circuit for the skin temperature sensor (operational amplifier, block 32) is similar to the air temperature sensor circuitry.

Software version 10.n and 20.n:

The temperature of 32.0 to 39.0 °C is represented by 0.0 to 5.0 V input voltage of the ADC.

Software version 11.n and 21.n (units with ThermoMonitoring):

The temperature of 30.0 to 42.0 °C is represented by 0.0 to 5.0 V input voltage of the ADC.

### **2.2.2.6 Testing of the skin temperature sensor circuit (37)**

The accuracy of the skin temperature sensor circuitry is checked every 10 minutes as part of the 10 minute test. On the Analog PCB the relay K1 or by FET transistors on newer devices as of 1996 replaces software controlled the sensor for a short time with a fixed precision resistor with the temperature equivalent of 36.0 °C. If this reference temperature is measured with an error of more than 0.3 °C, a sensor alarm (Err) is caused.

In addition to the automatic accuracy test of the skin temperature sensor measurement, the operator can manually test the circuit by pressing the "Check 36 °C" key. This procedure in the same manner replaces the skin temperature sensor with the reference resistor by means of relay K1 or FET transistors. The operator can look for the correct display of 36 °C.

In order to detect a defective relay K1 or FET transistors which could cause a complete corrupted skin temperature measurement and control because of the fixed reference resistor a software test routine is implemented. This routine analyzes the skin temperature sensor data and makes a plausibility test. The basic assumption is that the reference resistor will lead to a very stable temperature value with virtually no drift. If, in a 20 minute time interval, the temperature drift is less than 0.003 °C it is assumed that the reference resistor is measured instead of the skin temperature sensor. A sensor failure alarm (Err) will then be generated.

### **2.2.2.7 Skin temperature sensor alarm (32)**

The output voltage (proportional to temperature) of the first amplifier stage is compared for values that are outside the allowed range of temperature values. This could be caused by a short circuit in the probe or a broken sensor cable.

### **2.2.2.8 Skin temperature sensor detection**

Software version 10.n and 20.n: The plug of the skin temperature probe is coded in order to indicate that the sensor is plugged in. A 5 V pull up resistor is connected to ground by a

jumper in the plug whenever the sensor is plugged in. This voltage is sensed by the microprocessor via a port.

#### **2.2.2.9 Oxygen sensor A (41A), Inc. 8000 IC only**

The output voltage of the oxygen sensor cell A is adapted to the ADC by the input amplifier stage (33A). The output voltage of 0.0 mV to 120 mV is amplified to 0.0 V to 4.76 V.

#### **2.2.2.10 Oxygen sensor B (41B), Inc. 8000 IC only**

The output voltage of the oxygen sensor cell B is adapted to the ADC by the input amplifier stage (33B). Its amplification factor is reduced by the factor of 2.75 compared to the oxygen sensor A. This different amplification factor is later compensated for by software. After analog to digital conversion comparing signal B to the signal of oxygen cell A has to show the discrepancy in values to be within a certain window. Errors because of false addressing of the multiplexer are clearly detected. Resolution: 0.0 mV to 120 mV input voltage = 0.0 V to 1.73 V output voltage

#### **2.2.2.11 O<sub>2</sub> comparators (30A and 30B), Inc. 8000 IC only**

In addition to the microprocessor controlled check of the oxygen cell each cell is monitored with an individual comparator. These comparators are set to a trigger level of approx. 7 mV. If the output voltage falls below this limit, the relay (18) and the oxygen valve (3) are switched off and the oxygen sensor alarm is activated.

#### **2.2.2.12 Detection of sensor head position (43), Inc. 8000 IC only**

The position of the sensor housing at the hinge is sensed by two micro switches installed in the sensor housing and is evaluated via a PIA on the Motherboard PCB.

#### **2.2.2.13 Humidity sensor (42), Inc. 8000 IC only**

The output voltage of the humidity sensor is switched to the ADC via a voltage divider (34). Resolution: 0 to 100 % relative humidity = 0.55 to 4.31 V

#### **2.2.2.14 Reference for ADC (35)**

The reference voltage for the ADC is based on the +15 V and the -15 V supply voltage for the analog components. This allows monitoring the accuracy and function of the voltage regulators for these voltages.

#### **2.2.2.15 Multiplexer (28)**

The eight to one multiplexer selects the input signals for the ADC and is addressed by the outputs of the PIA. The addressing of the multiplexer is also reread by the PIA to detect addressing errors. Any addressing error will lead to an Inop alarm.

#### **2.2.2.16 A/D Converter (27)**

The A/D converter digitizes the analog signals with a resolution of 12 bit. The 12 bit words are read by two consecutive 8 bit data readings.

#### **2.2.2.17 Over-temperature alarm (16)**

Any over-temperature that is detected either by the microprocessor or by the redundant hardware is stored in the bistable relay and drives the relay (12) to switch off the heaters. The hardware detection is set to the trigger level of 40 °C, the software trigger level is set to 38 °C for set point values less than 37 °C and 40 °C otherwise. One contact of the bistable relay is used for monitoring of the sensor module position by the microprocessor through PIA 1. The second contact drives the power relay (12) that switches power on and off in the heating elements for air (1) and water (2). The bistable relay is reset by the microprocessor through one output of the PIA. This output signal is AC-coupled with a capacitor thus preventing the bistable relay from locking in case of a defective output port of the PIA.

#### **2.2.2.18 Fan failure alarm (6)**

The rotation of the fan wheel is detected by two permanent magnets in the wheel that induce pulses into a coil. These pulses are used to re-trigger a mono stable flip-flop. Its output is read by the microprocessor through PIA2. If the speed of the fan wheel falls below a certain limit, the mono stable flip-flop will not be re-triggered in time and the output will go to the high level. The function of this fan wheel monitoring circuit is tested by the microprocessor via PIA2. The microprocessor can purposely suppress the fan wheel pulses in-order to generate a fan wheel rpm failure signal.

### 2.2.2.19 Watchdog circuits (21)

Two watchdog circuits are used to supervise the program flow in the microprocessor. The watchdogs are basically mono stable flip-flops that require to be re-triggered in a certain time to allow normal operation of the Incubator. One of the watchdogs is triggered by the interrupt driven routines, the other is triggered by the background software loop. Each of the watchdogs is addressed by one unique address and is dimensioned to elapse in 100 ms. The software is designed in a way that both watchdogs are re-triggered in time. Any hardware or software failure would affect the proper re-triggering and therefore cause one or both watchdogs to be activated. The outputs of the two mono stable flip-flops are combined and connected to all relevant power drivers in order to deactivate any actuator thus transferring the incubator into the safe mode. The signal transducer (22) is also activated independent of the software. The watchdog mono stable flip-flops are tested in the 10-Minute-Test.

### 2.2.2.20 +5 V voltage monitoring (19)

The digital supply voltage of 5 V is monitored by a window comparator for high and low voltage conditions. The limits are set to 4.4 V and 5.5 V. If the window comparator senses high or low voltage, the 24 V power supply for the solid state relays and the oxygen valves is interrupted by the relay (17). Via transistors V15 and V16 the comparator limits to test the function of the voltage monitoring can be adjusted. This is done by the software via ports CA2 and CB2 of PIA S1 (10-Minutes-Test).

Normal operation:	CA2 = L-level;	CB2 = H-level
Test upper limit:	CA2 = H-level;	CB2 = H-level
Test lower limit:	CA2 = L-level;	CB2 = L-level

The +5 V supply voltage is also monitored via a watchdog circuit (25A) on the CPU PCB (25). This watchdog circuit cannot be tested during operation because it triggers a reset.

### 2.2.2.21 Driving the actuators

Both air heater and humidifier are digitally controlled through the PIA1 and the solid state relays (13) and (14). The driver signal for the humidifier is read back by PIA2. The valve (Inc. 8000 IC only) is controlled by PIA1 and driven by a power transistor on the Motherboard PCB. The driver signal is supervised by the second PIA.

### 2.2.2.22 Monitoring of air heating

The driver and status of the air heating are monitored by an insulated current sensor at the secondary side of high voltage. The output signal is monitored via PIA2.



#### **2.2.2.23 Thermal switches heaters**

The air heater is protected by a thermal circuit breaker (9) that interrupts the power for the heater in case of over-temperatures. The humidifier is equipped with two thermal switches. One is used to interrupt the power (10) in case of severe overheating. The second thermal switch (7) operating at a lower temperature level is used to indicate the microprocessor that the water supply is empty which causes a rise in the temperature of the humidifier.

#### **2.2.2.24 Display driver and keyboard interface (26)**

The 7 segment display and the LED's are driven by special integrated circuits which are used in every module. The keyboard interface of the Air Temperature Display PCB is part of one of these circuits and reads all keys (button switches) from all modules.

#### **2.2.2.25 Mono stable flip-flop for INOP LED (24)**

The Inop LED is driven by a mono stable flip-flop with a time constant of 100 ms. This mono stable flip-flop is addressed by the unique address during the background routine.

#### **2.2.2.26 Power supply and battery (15)**

The power supply delivers voltages of +5 V, +15 V, -15 V and +24 V. A NiCad battery integrated into the power supply serves as the power source in case of power failure to drive the signal transducer and the power failure LED.

#### **2.2.2.27 Power fail detection (23)**

If half waves of the AC power supply voltage are missing because of disturbances or interruptions or because the Incubator has been switched off at the main power switch, a NMI (Non Maskable Interrupt) is activated. The software will immediately check the position of the main power switch and based on its position initiate a "cold" or "warm" start.

#### **2.2.2.28 Driver for the beeper (22)**

The beeper is driven by a digital signal of PIA1. Very short pulses to the beeper are suppressed by a filter to avoid spurious noise during testing. In case of a power failure the beeper is activated independently of the microprocessor and powered by the battery.

### **2.2.2.29 Power on (11)**

The power switch controls the supply voltage for the mains power relay K1 and K5. The supply voltage is generated by a small auxiliary transformer.

### **2.2.2.30 Fan for additional cooling (44)**

In order to shorten the time required for cooling down the Incubator an additional fan placed in the electronics is activated by air heater feedback signal. These pulses are used for re-triggering a mono stable flip-flop. The fan is on whenever the air heater is shut off.

## **2.3 Description of safety facilities**

### **2.3.1 Alarm display**

The incubator features a graded alarm behavior. Faults occurring are indicated as a function of their significance. The alarms for set value deviations, over-temperature and water shortage feature an intermittent alarm tone which can be deactivated for 10 minutes. All other faults are signalled by a continuous tone which cannot be silenced. In addition the corresponding alarm LED flash. Each individual alarm likewise leads to an indication on the central alarm LED (not available on Incubator 8000 SC / NC with software version 10.n).

#### **2.3.1.1 Alarms in the event of set value deviations, over-temperature and water shortage**

- Actual value display or desired value display humidity Inc. 8000 SC / NC of module concerned flashes.
- The corresponding alarm LED flashes.
- Intermittent alarm tone (can be deactivated for 10 min).

The alarm tone for the set value/actual value difference  $> -1.5\text{ °C}$  air temperature is suppressed automatically for 30 minutes following switch-on of the Incubator. If during this period the actual value is at least  $1.5\text{ °C}$  below the set value, the alarm and the current suppression time are indicated by the corresponding LED. In this case the actual value display does not flash. The alarm suppression time is reset prematurely as soon as the actual air temperature value is no longer  $1.5\text{ °C}$  below the set value.

The over-temperature alarm is stored by means of a bipolar relay and must be reset with the reset button after termination of the over-temperature status. All other alarms are reset automatically once the cause of the fault has been eliminated.

In the event of suppressed audio alarm, the corresponding alarm LED and the central alarm LED (not available on Incubator 8000 SC / NC with software version 10.n) light up continuously; the horn is off. The yellow LED above the switch-off button indicates that the alarm has been acknowledged.

Should a further alarm situation occur during the course of alarm suppression, the audio alarm is immediately re-activated and the alarm suppression time reset. Depending on the type of fault, this alarm can also be suppressed again. The reactivation time for the first alarm tone is then extended by the difference in time between the two alarms.

### **2.3.1.2 Sensor alarms, fan failure alarm**

Faults in the sensors for air temperature, skin temperature, oxygen concentration (Inc. 8000 IC only) and humidity (Inc. 8000 SC / IC only) as well as fan faults result in the following alarm messages:

- Three dashes (air and skin temperature) or two dashes (O2, humidity) flash in the respective actual value display.
- In the event of a fan fault the air temperature actual value flashes.
- The corresponding alarm LED flashes.
- Continuous horn tone (cannot be deactivated).

With respect to the sensor alarms for oxygen concentration (Inc. 8000 IC only) and humidity (Inc. 8000 IC only), the alarm is reset following switch-off of the module concerned and further operation can be continued with the other functions. The same applies to the skin temperature module, however, the defective sensor must first be removed in this case.

### **2.3.1.3 Module fault**

Hardware faults affecting a single module result in the following alarm messages for the skin temperature, oxygen concentration and humidity modules:

- The letters "Err" flash up on the corresponding actual or desired value display if the module is switched on or appear in steady form if the module is switched off.
- INOP-LED lights up if module is switched on.
- Continuous horn tone (cannot be deactivated) if module is switched on.

The functions of the other modules which are working properly are retained.

#### **2.3.1.4 INOP**

Serious hardware or software faults result in complete failure of the incubator. The following alarm messages are given:

- The INOP-LED lights.
- Continuous horn tone (cannot be deactivated).

The equipment is not serviceable.

Additional for Incubator 8000 IC:

If after switch-off of the O<sub>2</sub> module within a few minutes an increase of the O<sub>2</sub> concentration by more than 3 Vol. by. % is detected this will also lead to an INOP message:

- INOP-LED lights.
- Continuous horn tone (cannot be deactivated).

The current O<sub>2</sub>-actual value is displayed flashing.

### **2.3.2 Software**

All software routines described below (except test for RAM battery backup) that detect a failure condition will cause an INOP alarm.

#### **2.3.2.1 RAM test**

After power is turned on, a complete test of the RAM (Random Access Memory) addressing range of the microprocessor is performed. Specific bit patterns are used and move through the RAM area. All RAM cells that are not used by the software are set to zero. During normal operation of the software an ongoing RAM test is performed in the background. During this test blocks of the RAM are swapped into a reserved RAM area. The RAM is then tested with the bit patterns test scheme. All data transfer from and to the data block under test is secured by CRC-calculations (Cyclic Redundancy Check).

#### **2.3.2.2 Test of RAM Battery Backup**

After power is turned on, the battery backed up RAM is checked by analyzing the contents of 5 test addresses. If a mismatch was detected, the continuous tone appears for approximately 4 seconds. Then the test addresses are rewritten with the proper information and a cold start is performed which does not rely on the corrupted data in the battery backed up RAM.

### **2.3.2.3 ROM Test**

After power is on the signature of the ROM (Ready Only Memory) is tested by calculating the checksum (CRC). During normal operation an ongoing ROM test is performed in background. Approximately every 5 minutes the whole ROM contents is tested completely. The ROM cell contents is tested for non-equivalence by EXOR operations.

### **2.3.2.4 Timer Test**

After power is on, the timers are programmed to a certain time. The operation of the timers is then compared with a software timer that consists of a program loop.

### **2.3.2.5 PIA Test**

The PIA (Peripheral Interface Adapter) initialization is checked upon "power on" as part of the self check routines.

### **2.3.2.6 Display Test**

The internal RAM of the display and keyboard control IC (Integrated Circuit) is reread after every writing of new data into the chip. That read data is then compared with the original data.

### **2.3.2.7 CPU Test**

The test of the CPU (Central Processing Unit) is performed automatically by the two cyclically executed routines for RAM test and 16 bit CRC calculation and by the logical program tracing.

### **2.3.2.8 Logical Program Tracing**

All program execution, whether interrupt driven or part of the background loop, is supervised by the logical program tracing scheme. Before every return of a subroutine, specific alterations of data in a special data area by using all CPU-commands and addressing modes are performed. Only when the predicted program flow is followed properly, these data manipulations will lead to the correct results which are supervised. If, because of a hardware or software failure, the program flow is affected, the logical program sequence is changed and will be detected as being incorrect by the logical program tracing scheme.

### **2.3.2.9 10 Minute Test**

The 10 minute test is implemented to test every 10 minutes all testable hardware safety functions.

## **3 Detailed description of Incubator 8000 IC / SC / NC sub-assemblies**

- Heating unit
- Electronics module:
  - a. Keyboard
  - b. PCB Display Air Temperature
  - c. PCB Display Options
  - d. PCB Display Humidity (only Inc. 8000 SC)
  - e. PCB CPU
  - f. PCB Analog
  - g. PCB Power Pack
  - h. PCB Motherboard
  - i. PCB Switch
  - j. PCB Fan
  - k. Voltage regulator on side panel
  - l. PCB Filter
- Air temperature sensor (only Inc. 8000 SC / NC)
- Environmental sensor housing (only Inc. 8000 IC)
- Skin temperature sensor
- Valve block (only Inc. 8000 IC)

### **3.1 Heating unit**

- The following function blocks may be found on the unit:
- Fan motor
- Air heating with over-temperature protection (unsoldering protection)
- Humidifier with over-temperature protection (manually re-settable)

- Mains transformer
- Sensor to monitor number of revolutions at impeller (inductive fan monitoring)
- Semiconductor relay for galvanically separated triggering of air heating and humidifier
- PCB Unit:
  - a. mains auxiliary transformer for mains connection
  - a. mains connection relays
  - b. safety relays for heatings and O<sub>2</sub> valves
  - c. fuses for mains input and internal supply voltages

The unit forms the intersection between supply voltage and secondary side of the electronics. A voltage higher than + 33 V is not supplied to the other incubator components.

### **3.1.1 Detailed description of function blocks of Unit PCB**

#### **3.1.1.1 Mains connection**

Incubator 8000 is connected to the mains via the auxiliary transformer L1 to which the mains relays K1 and K5 are connected at the secondary to +12 V. The relay is connected via pins X1/1 and X1/27 via the standby switch at the front panel. Through the relay contacts the mains voltage is supplied to the consumers.

#### **3.1.1.2 Cutoff relay K2 for heating**

Relay K2 is a safety relay to cut off the mains voltage supply of the air and humidifier heating.

#### **3.1.1.3 Cutoff relay K3 for O<sub>2</sub> valves (Inc. 8000 IC only)**

Relay K3 is a safety relay to cut off the supply voltage of the O<sub>2</sub> valves.

#### **3.1.1.4 Cutoff relay K4 for +24 V**

Relay K4 is a safety relay to cut off simultaneously the supply voltage of the semiconductor relays, of the air and humidifier heating and of the O<sub>2</sub> valves.



### **3.1.1.5 24 V supply voltage**

The 24 V a.c. voltage at TP22 and TP23 supplies the fan motor via TP30 to TP33. Moreover, this a.c. voltage is rectified on the Unit PCB and supplies voltage to the semiconductor relays, the 02 valves and the safety relays.

## **3.2 Electronics Module**

The electronics modules are a sub-assembly to control the air temperature, the 02 concentration (Inc. 8000 IC only) and the humidity. The skin temperature module also facilitates control of the air temperature in dependence of a child's skin temperature. The electronics module comprises the following function blocks:

- Keyboard
- Display Air Temperature PCB
- Display PCB (skin temperature with SW 10.n and 20.n, 02-control, humidity control Inc. 8000 IC)
- Display Humidity PCB (only Inc. 8000 SC / NC))
- CPU PCB
- Analog PCB
- Power Pack PCB
- Motherboard PCB
- Switch PCB
- 5 V voltage regulator
- Display Skin PCB (as of SW 11.n and 21.n)

### **3.2.1 Keyboard**

The keypad is evaluated on the PCB Display Air Temperature.

### **3.2.2 Display Air PCB**

The PCB Display Air indicates the set and the actual values, the alarms and operating conditions for the operating mode air temperature control as well as for the evaluation of the whole keypad. Furthermore the LEDs which are not related to the module are on this PCB.

#### **3.2.2.1 Keypad and display interface module 8279**

The programmable keypad and display interface module 8279 (D1) takes over the display control of the Display Air PCB as well as the inquiry of the whole Incubator 8000 keypad. The display control is done by means of the multiplexer. Ports A0 to A3 and B0 to B3 are driven as



B-Bit channel, via ports SL0 to SL1 and decoder D2 the displays are read in columns. The keypad inquiry is also done by means of the multiplexer method via ports R0 to R7. Via ports SL0 to S11 and decoder D2 the column reading of the keypad is carried out.

### **3.2.2.2 INOP-LED**

The INOP-LED V 34 is triggered by an external signal (watchdog PCB Motherboard) via pin X1/4.

### **3.2.2.3 Mains failure LED**

The mains failure LED (V26) is externally driven via pins X1/19 and X1/21 (Power Pack PCB).

### **3.2.2.4 Working LED**

The working LED V27 is directly connected to the supply voltage +5 V via the series resistor R15.

## **3.2.3 Display PCB**

### **3.2.3.1 Display interface module**

The programmable keypad and display interface module 8279 (D1) takes over the display control on the Display PCB. The output is done with the multiplexer method. Ports A0 to A3 and B0 to B3 are driven as 8-bit channel, via ports SL0 to S11 and a decoder the column reading of the displays is effected.

### **3.2.3.1 Use of Display PCB**

On units with software version 10.n and 20.n:

- O2
- Skin
- Humidity (Inc. 8000 IC only)

On units with software version 11.n and 21.n:

- O2
- Humidity (Inc. 8000 IC only)

### 3.2.4 Display Humidity PCB (Inc. 8000 SC / NC only)

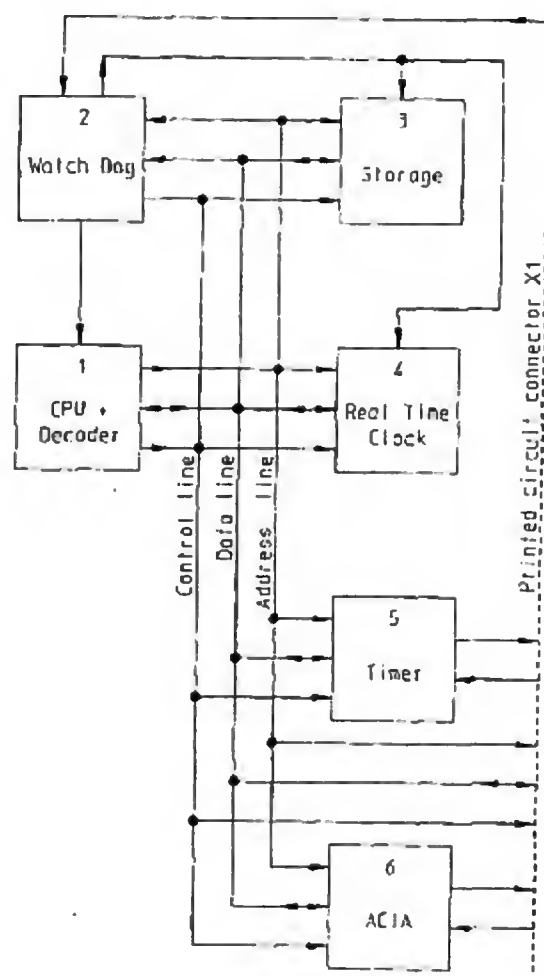
Functions like PCB Display. On this PCB only the necessary display elements are fitted.

### 3.2.5 CPU PCB

#### 3.2.5.1 Intended use

The CPU Standard 2 PCB is a sub-assembly which forms the center of electronical driving in many Dräger devices. As of 1993 a CPU Incubator PCB is used in all Incubators 8000 series.

#### 3.2.5.2 Block diagram



Block 1 includes the CPU (UP 6802) with clock oscillator and address decoding.  
 Block 2 contains the entire data and program storage (up to 64 kByte RAM/EPROM). With ACIA in block 3 a serial interface is provided but is not fitted for Incubator 8000 series.

TIMER module 4 enables timer functions and may be operated with internal and several external clock pulses.

A battery-buffered REAL TIME CLOCK 5 provides time and date (not fitted for Incubator 8000 series).

### 3.2.5.3 Detailed description

The CPU Standard 2 PCB or the CPU Incubator PCB is a microprocessor system featuring the microprocessor 6802, which contains the entire data and program storage area and various peripheral modules. Voltage monitoring and watchdog logic are also provided (CPU Standard 2 PCB only).

The address, data and control lines of the CPU are connected to the operating voltage by way of pull-up resistance networks, so as to obtain level matching with respect to the subsequent HCMOS modules. The address and control lines are buffered directly at the CPU with D2, D3 and D5 in order to enable the assembly to be operated in DMA mode. These driver modules are controlled by the signal BA.

The address decoder consists of the programmable module D6 and the subsequent decoder D7. Chip select signals for the memory modules D8 to D12 and one select signal each for the internal I/O modules, the external I/O modules and the data bus driver are generated in D6. The programmability of D6 makes it possible - together with the jumper fields X2 to X5, X8 - to have extremely flexible assembly with various memory modules. The signal BA at D7 is used to prevent an external CPU (DMA mode) having memory access to the I/O modules.

The timer module D13 can be operated with an internal and an external clock pulse. One of the three clock pulses 100 Hz, 1 kHz, 10 kHz can be supplied to each clock input C1, C2, C3 via the jumper field X6. The three gate inputs G1, G2, G3 and the timer outputs Q1, QZ, Q3 are routed to the printed circuit board connector X1.

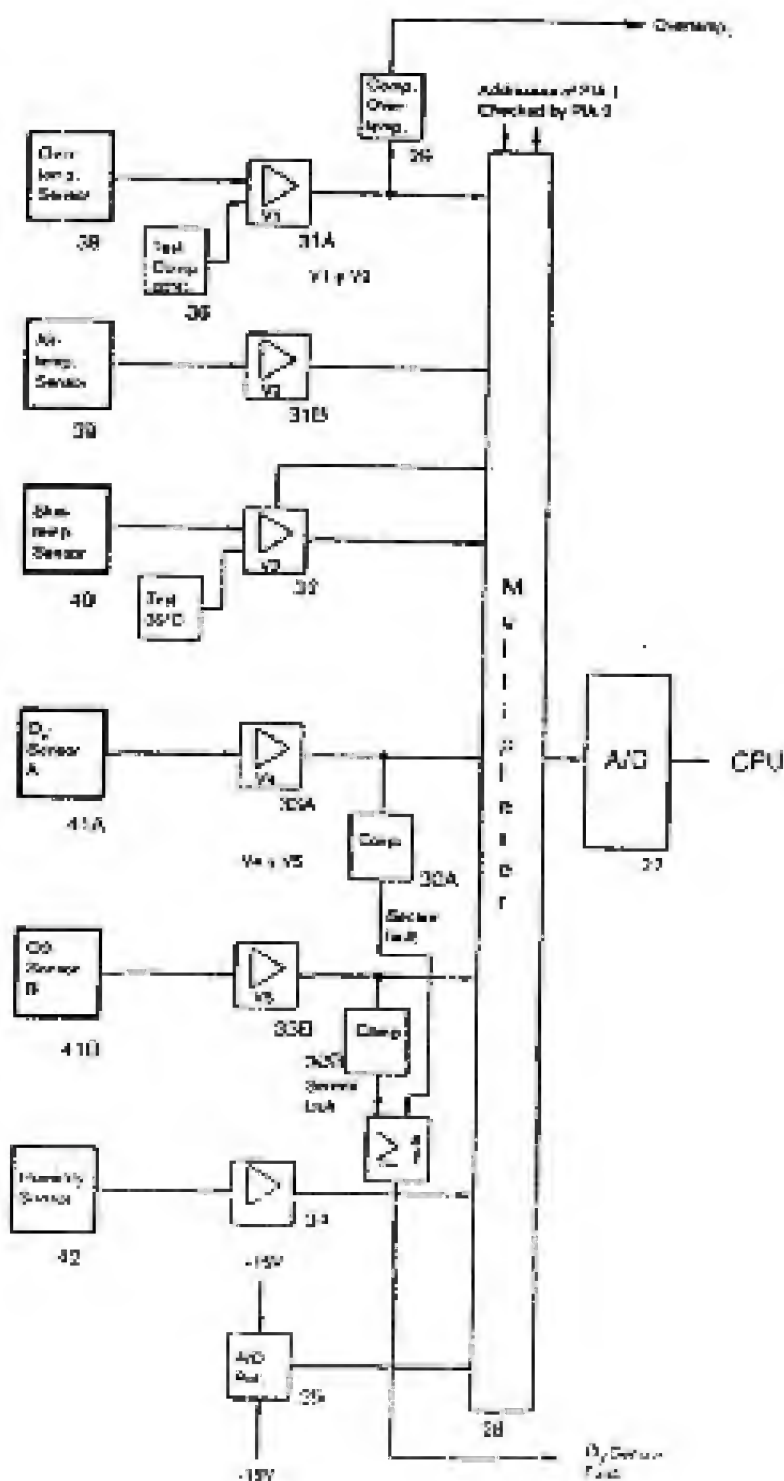
## 3.2.6 Analog PCB

### 3.2.6.1 Intended use

Three different versions of the Analog PCB are available:

82 00 770	Without skin temperature measurement
82 00 920	With skin temperature measurement (1 channel). For software version 10.n and 20.n only.
82 90 680	With skin temperature measurement (2 channels for Thermomonitoring). For software version 11.n and 21.n only.

### 3.2.6.2 Block diagram



### 3.2.6.3 Detailed description of function blocks

- a. air temperature sensor
- b. over-temperature sensor
- c. over-temperature comparator
- d. test over-temperature comparator
- e. skin temperature sensor
- f. test skin temperature sensor circuit
- g. skin temperature-sensor alarm
- h. skin temperature sensor detection
- i. O<sub>2</sub> sensor A
- j. O<sub>2</sub> sensor B
- k. O<sub>2</sub> comparator
- l. detection of sensor head position
- m. humidity sensor
- n. A/D converter reference voltage
- o. Multiplexer
- p. A/D converter

#### a. air temperature sensor

The air temperature sensor is part of the feedback loop of an operational amplifier and supplies an outlet voltage proportional to the temperature which is adapted to the input voltage range of the A/D converter via a second amplification stage. Resolution: 0.0 °C to 60.0 °C = 0.0 V to 5.0 V.

#### b. over-temperature sensor

The over-temperature sensor is installed in the same housing as the air temperature sensor and serves as redundant measuring system for the air temperature. The amplification factor and thus the output signal is not equal to the output signal of the air temperature sensor. The air temperature and the over-temperature sensor are monitored by the software. If the measured temperatures deviate by more than 0.5 °C a sensor alarm is given. The over-temperature sensor is part of the feedback loop of an operational amplifier and supplies an outlet voltage proportional to the temperature which is adapted to the input voltage range of the A/D converter via a second amplification stage. Resolution: 0.0 °C to 50.0 °C = 0.0 V to 5.0 V.

#### c. over-temperature comparator

The output voltage of the over-temperature sensor is additionally evaluated by a comparator whose response limit is set to 40.0 °C. Independent of the microprocessor system in the event of over-temperature the heating is switched off via this comparator and thus the device is put

into a safe condition. The over-temperature condition is stored by a bipolar relay on the Motherboard PCB. The heating control can only be released by acknowledgement via a reset button after the temperature has fallen below the comparator limit.

d. testing of over-temperature comparator

The function of the over-temperature comparator is checked software-controlled every 10 minutes. On the Analog PCB the relay (K2) or by FET transistors on newer devices as of 1996 substitutes for a short time the over-temperature sensor with a fixed resistor simulating a temperature higher than 40.0 °C.

e. Skin temperature sensor

The skin temperature sensor is part of the feedback loop of an operational amplifier and supplies an output voltage proportional to the temperature which is adapted to the input voltage range of the A/D converter via a second amplification stage.

Software version 10.n and 20.n:

The temperature of 32.0 to 39.0 °C is represented by 0.0 to 5.0 V input voltage of the ADC.

Software version 11.n and 21.n (units with Thermomonitoring):

The temperature of 30.0 to 42.0 °C is represented by 0.0 to 5.0 V input voltage of the ADC.

f. Testing of the skin temperature sensor circuit

The accuracy of the skin temperature sensor circuitry is checked every 10 minutes as part of the 10 minute test. On the Analog PCB the relay K1 or by FET transistors on newer devices as of 1996 replaces software controlled the sensor for a short time with a fixed precision resistor with the temperature equivalent of 36.0 °C. If this reference temperature is measured with an error of more than 0.3 °C, a sensor alarm (Err) is caused.

In addition to the automatic accuracy test of the skin temperature sensor measurement, the operator can manually test the circuit by pressing the "Check 36 °C" key. This procedure in the same manner replaces the skin temperature sensor with the reference resistor by means of relay K1 or FET transistors. The operator can look for the correct display of 36 °C.

In order to detect a defective relay K1 or FET transistors which could cause a complete corrupted skin temperature measurement and control because of the fixed reference resistor a software test routine is implemented. This routine analyzes the skin temperature sensor data and makes a plausibility test. The basic assumption is that the reference resistor will lead to a very stable temperature value with virtually no drift. If, in a 20 minute time interval, the temperature drift is less than 0.003 °C it is assumed that the reference resistor is measured instead of the skin temperature sensor. A sensor failure alarm (Err) will then be generated.

g. Skin temperature sensor alarm

The output voltage (proportional to temperature) of the first amplifier stage is compared for values that are outside the allowed range of temperature values. This could be caused by a short circuit in the probe or a broken sensor cable.

h. Skin temperature sensor detection

Software version 10.n and 20.n: The plug of the skin temperature probe is coded in order to indicate that the sensor is plugged in. A 5 V pull up resistor is connected to ground by a jumper in the plug whenever the sensor is plugged in. This voltage is sensed by the microprocessor via a port.

i. Oxygen sensor A, Inc. 8000 IC only

The output voltage of the oxygen sensor cell A is adapted to the ADC by the input amplifier stage (33A). The output voltage of 0.0 mV to 120 mV is amplified to 0.0 V to 4.76 V.

j. Oxygen sensor B, Inc. 8000 IC only

The output voltage of the oxygen sensor cell B is adapted to the ADC by the input amplifier stage (33B). Its amplification factor is reduced by the factor of 2.75 compared to the oxygen sensor A. This different amplification factor is later compensated for by software. After analog to digital conversion comparing signal B to the signal of oxygen cell A has to show the discrepancy in values to be within a certain window. Errors because of false addressing of the multiplexer are clearly detected. Resolution: 0.0 mV to 120 mV input voltage = 0.0 V to 1.73 V output voltage

k. O<sub>2</sub> comparators, Inc. 8000 IC only

In addition to the microprocessor controlled check of the oxygen cell each cell is monitored with an individual comparator. These comparators are set to a trigger level of approx. 7 mV. If the output voltage falls below this limit, the relay (18) and the oxygen valve (3) are switched off and the oxygen sensor alarm is activated.

l. Detection of sensor head position, Inc. 8000 IC only

The position of the sensor housing at the hinge is sensed by two micro switches installed in the sensor housing and is evaluated via a PIA on the Motherboard PCB.



m. Humidity sensor, Inc. 8000 IC only

The output voltage of the humidity sensor is switched to the ADC via a voltage divider (34).  
Resolution: 0 to 100 % relative humidity = 0.55 to 4.31 V

n. Reference for ADC

The reference voltage for the ADC is based on the +15 V and the -15 V supply voltage for the analog components. This allows monitoring the accuracy and function of the voltage regulators for these voltages.

o. Multiplexer

The eight to one multiplexer selects the input signals for the ADC and is addressed by the outputs of the PIA. The addressing of the multiplexer is also reread by the PIA to detect addressing errors. Any addressing error will lead to an Inop alarm.

p. A/D Converter

The A/D converter digitizes the analog signals with a resolution of 12 bit. The 12 bit words are read by two consecutive 8 bit data readings.

## 3.2.7 Power Pack PCB

### 3.2.7.1 Intended use

PCB Power Pack serves the rectification of the supply voltages +15 V and -15 V. By means of half-wave monitoring a power fail or mains interrupt is recognized. If the mains voltage fails a battery-buffered audible alarm is given by a beeper on the PCB and an optical alarm is given by an external LED. During operation the beeper is driven by an external signal.



### 3.2.7.2 Detailed description of function blocks

- a. Supply voltage +15 V
- b. Supply voltage -15 V
- c. Supply voltage +5 V
- d. Power-fail recognition
- e. Driving of beeper
- f. Storage battery charging connection

- a. Supply voltage +15 V

The AC-voltage at pins 1 a/c and 2 a/c is rectified, filtered and routed to the +15 V fixed voltage regulator.

- b. Supply voltage -15 V

The AC-voltage at pins 3 a/c and 4 a/c is rectified, filtered and routed to the -15 V fixed voltage regulator.

- c. Supply voltage +5 V

The AC voltage at pins 5/6 a/c and 7/S a/c is rectified, filtered and routed to the 5 V fixed voltage regulator which is attached outside.

- d. Power-fail recognition

The AC-voltage at pins 1 a/c and 2 a/c is processed for triggering of mono flop D1. If a half-wave fails or when the device is switched off an NM1 is released by the output of the mono. Via pin 28 a/c the position of the mains switch at the time of the power fail is evaluated and thus a flag is generated for cold-/warmstart decision for the software after the mains voltage has returned.

- e. triggering of beeper

During operation the beeper is driven via pin 24 a/c. The beeper is active when the H-level is present at this pin. Capacitor C12 and diodes V33 and V34 prevent a short response of the beeper when the device is switched off. In case of power fail the beeper is fed by the storage battery via the closed mains switch auxiliary contacts. Via pin 23 a/c an external LED is switched on.

- f. storage battery switching circuit

During operation the storage battery is connected to a charging circuit consisting of R6 to R9 and transistor V23.

## 3.2.8 Motherboard PCB

### 3.2.8.1 Intended use

The Motherboard PCB interconnects all PCBs of Incubator 8000 series. Moreover, the components for the digital signal processing (except CPU) are installed on this PCB.

### 3.2.8.2 Detailed description of function blocks

- a. address decoder
- b. PIA
- c. over-temperature alarm
- d. fan failure alarm
- e. watchdogs
- f. +5 V voltage monitoring
- g. indication air heating
- h. monoflop for INOP-LED
- i. triggering of additional fan

- a. address decoder

Via the address decoders D4 and D5 the CS-signals from the address range 8XXXh are generated.

- b. PIA

PIA D1 is addressed via the addresses 8010h to 8013h, PIA D2 via addresses 8020h to 8023h.

Assignment of PIA Ports D1 (E = input, A = output)

Port	Function
PA0 E	Indication over-temperature
PA1 E	Code skin temperature
PA2 E	Code 02
PA3 A	Addressing of Multiplexer (A0)

PA4 A	Addressing of Multiplexer (A1)
PA5 A	Addressing of Multiplexer (A2)
PA6 E	Fan interference/failure
PA7 A	Addressing Multiplexer
PB0 A	Triggering air heating
PB1 A	Triggering humidifier heating
PB2 A	Triggering 02-valve 1
PB3 A	Triggering 02-valve 2 (not used)
PB4 A	Reset over-temperature alarm
PB5 A	Check 36 °C
PB6 A	Relay over-temperature alarm and relay 02-cut-off
PB7 A	Beeper
CA1	free
CA2 A	Test +5 V voltage monitoring, upper limit
CB1	free
CB2 A	Test +5 V voltage monitoring, lower limit

Assignment of PIA Ports D2, E = input, A = output)

Port	Function
PA0 E	Code humidity
PA1 E	Water shortage
PA2 A	DW bus, external alarm (not used)
PA3 E	Indication addressing of Multiplexer (A0)
PA4 E	Indication addressing of Multiplexer (A1)
PA5 E	Indication addressing of Multiplexer (A3)
PA6 E	Indication Check 36 °C
PA7 E	Indication air heating
PB0 E	Code of sensor head position, switch 1
PB1 E	Indication humidifier heating
PB2 E	Indication 02-valve 1
PB3 E	Indication 02-valve 2 (not used)
PB4 E	Code of sensor head position, switch 2
PB5 A	Test over-temperature comparator
PB6 E	NMIQ: evaluation of NMI for cold-/warm start
PB7 E	Code mains switch on/off
CA1	free
CA2	free
CB1	free
CB2 E	Test fan failure alarm

c. over-temperature alarm

The bistable relay for the over-temperature alarm is installed on the Motherboard PCB. The excitation winding is triggered by the hardware via X2/20c from the PCB Analog and by the software via port PB6 from PIA D1. By contact K1.1 the relay position is read in and evaluated via port PA0 of PIA D1. Through contact K1.2 a cutoff relay is driven for the actuators. Excitation of the reset winding is done via port PB4 of PIA D1. C16 prevents continuous driving of the reset winding due to a defective port PB4 and thus that a pick up of the relays in the event of over-temperature is made impossible.

d. fan failure alarm

The fan is monitored by the voltage pulses induced in a coil by two permanent magnets which are attached at the impeller. The negative pulse triggers the mono flop D6A via the inverting amplifier N1. Via port PA6 of PIA D1 the signal is evaluated. Via port CB2 of PIA D2 the circuit function may be tested by pulling down the input of the circuit to a lower voltage level. Thus the fan pulses become ineffective.

e. watchdogs

Mono flops D3A and D3B form the two watchdogs for driving of the heatings and the valves. The watchdogs monitor the chronological program flow, separate for background and IRQ-level. Mono D3A is re-triggered via address 8030h in the background, mono D3B via address 8040h in the IRQ. The maximum re-triggering time is 100 ms. Both output signals are interconnected logically and with a further interconnection of the trigger signals for the heatings and valves lead to a release resp. blocking of these actuators. Moreover, in case one of the mono flops is elapsed the beeper is activated independent of the software.

f. +5 V voltage monitoring

The digital supply voltage of 5 V is monitored by a window comparator for high and low voltage conditions. The limits are set to 4.4 V and 5.5. V. If the window comparator senses high or low voltage, the 24 V power supply for the solid state relays and the oxygen valves is interrupted by the relay (17). Via transistors V15 and V16 the comparator limits to test the function of the voltage monitoring can be adjusted. This is done by the software via ports CA2 and CB2 of PIA S1 (10-Minutes-Test).

Normal operation:	CA2 = L-level;	CB2 = H-level
Test upper limit:	CA2 = H-level;	CB2 = H-level
Test lower limit:	CA2 = L-level;	CB2 = L-level

The +5 V supply voltage is also monitored via a watchdog circuit (25A) on the CPU PCB (25). This watchdog circuit cannot be tested during operation because it triggers a reset.

g. indication air heating

The indication of the air heating connection state is done from the supply voltage side through a converter on the PCB Unit. With this sinusoidal signal a mono flop connection is re-triggered and the output signal of PA7 of PIA D2 is evaluated.

h. Mono flop for INOP-LED

Via another monoflop (D6B) the INOP-LED is driven. The time constant is 100 ms. The mono is re-triggered via address 8050h.

i. triggering of additional fan

A mono-flop is installed on the printed circuit board, which is triggered by the indication impulses generated by the air heating via the current transformer. Via this mono-flop a fan is driven as soon as the air heating becomes inactive. The time constant for the mono flop is 1.36 s.

### 3.2.9 Switch PCB

The standby-switch with three independent switching contacts is installed on the Switch PCB. Switching contact S1.1 closes mains relay K1 on the Unit PCB. By means of switching contacts S1.2 and S1.3 the horn and the mains failure LED - supplied by the storage battery on the Power Pack PCB - are triggered in the event of power failure.

### 3.2.10 +5 V voltage regulator

The AC voltage of the transformer of the unit is rectified on the Power Pack PCB and is stabilized with the 5 V voltage regulator on the right side panel of the electronic module.

### 3.3 Air temperature sensor Inc. 8000 SC / IC

The air temperature sensor comprises 2 NTCs.

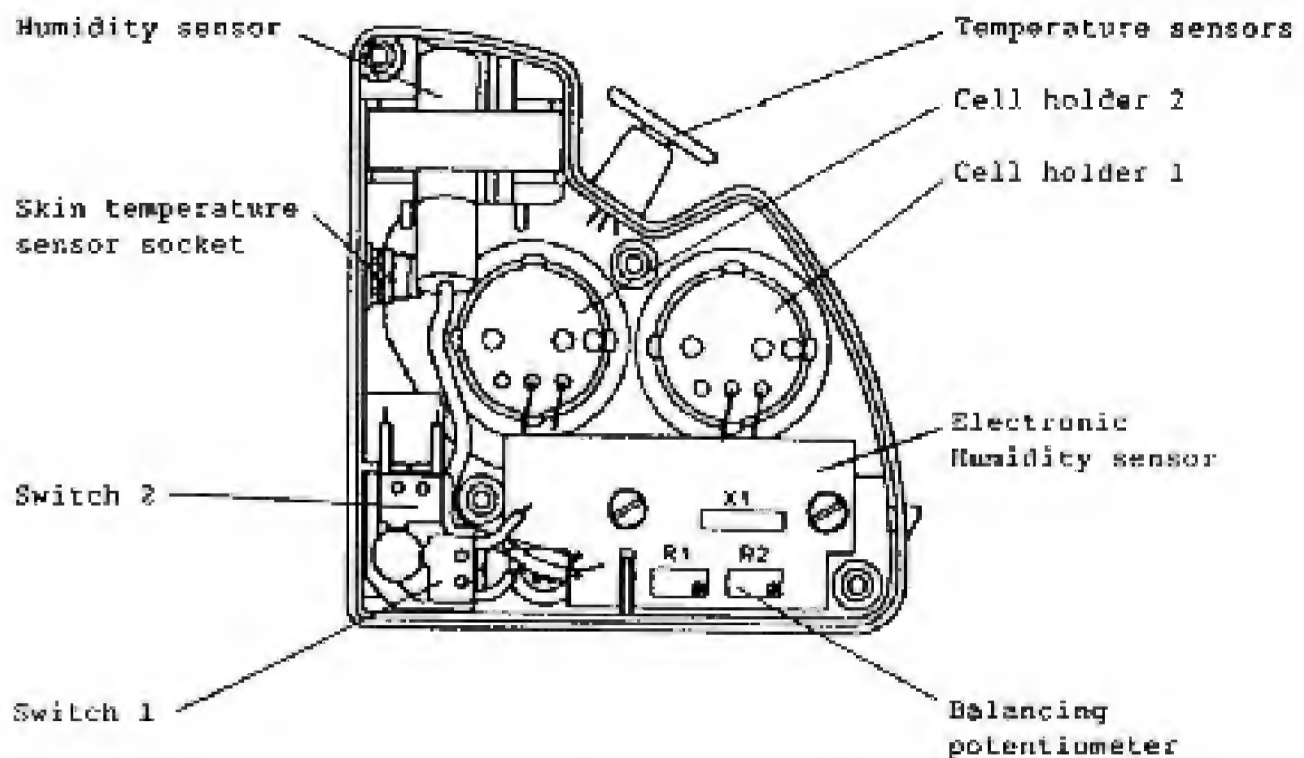
Temperature in °C	Resistance in Ohm
20	6246.0
21	5970.8
22	5709.4
23	5460.9
24	5224.7
25	5000.0
26	4786.1
27	4582.5
28	4388.8
29	4204.4
30	4028.7
31	3861.2
32	3701.6
33	3549.6
34	3404.6
35	3266.3
36	3134.4
37	3008.6
38	2888.5
39	2773.9

### 3.4 Climate sensor housing Inc. 8000 IC

#### 3.4.1 Intended use

The Incubator sensor serves measurement of the climatic conditions inside the Incubator 8000 IC. The air temperature, O<sub>2</sub>-concentration and the relative air humidity are monitored. On units with software version 20.n (without ThermoMonitoring) a skin temperature sensor may be connected to devices which are equipped accordingly.

#### 3.4.2 Arrangement



#### 3.4.3 Detailed description

##### 3.4.3.1 Temperature sensors

The air temperature sensor comprises 2 NTCs.

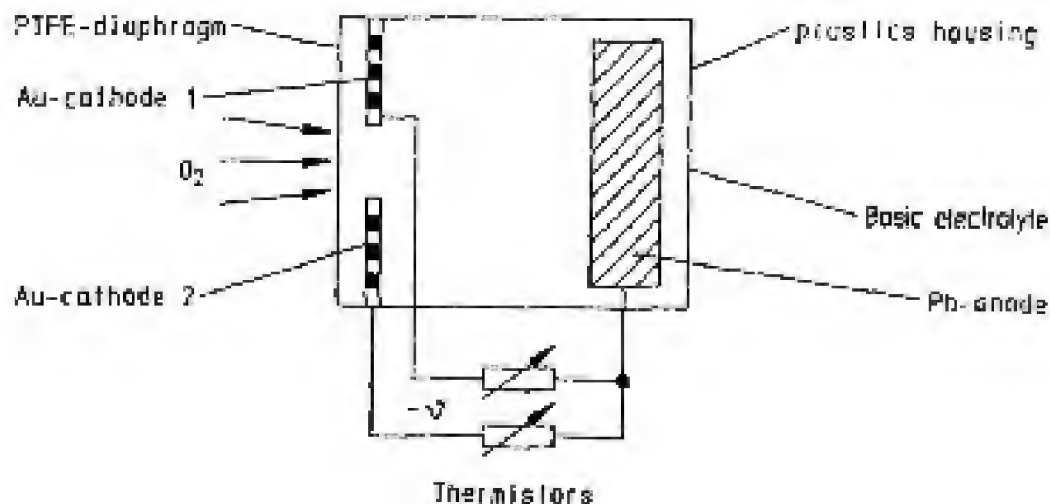
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32	3701.6
33	3549.6
34	3404.6
35	3266.3
36	3134.4
37	3008.6
38	2888.5
39	2773.9

### 3.4.3.2 O<sub>2</sub> sensors

There are two independent O<sub>2</sub>-cells in the climate housing one half of which is evaluated.

The sensor is designed according to the fuel cell principle as double cell, i.e. it is an electrochemical cell which builds up a voltage due to an ionic current. The cell comprises the capsule with the electrolytes, the lead anode and the gold cathode with teflon foil.



The oxygen to be measured diffuses through the teflon diaphragm, reacts at the gold cathodes and produces lead oxide and H<sub>2</sub>O at the lead anode. During this chemical process an electric voltage is produced which is proportional to the oxygen partial pressure. The gold cathode is



polarized positive, while the lead anode is negative. Since the lead anode is converted it has a limited lifetime. The internal resistance is determined by the electrode surface, the oxygen diffusion rate and the distances. It is also dependent on the sensor lifetime. In normal condition it is 700 Ohm. Like most of the chemical processes this one is also dependent on the temperature. Because of this temperature-independent resistors are connected in parallel to the sensor which correct the measuring-circuit voltage in conjunction with the internal resistance.

### 3.4.3.3 Humidity sensor

In the environmental sensor housing a capacitive humidity sensor with the evaluation electronics is installed. The output voltage is:

$$\text{Voltage humidity} = (7.1 \text{ V} / 100 \%) \times \text{rel. Humidity} (\%) + 1.05 \text{ V}$$

### 3.4.3.4 Microswitches

The position of the climate sensor housing is evaluated via two microswitches in four positions:

- 1 sensor housing swivelled in
- 2 sensor housing partly swivelled in
- 3 sensor housing hinged
- 4 sensor housing removed from the hinge

## 3.5 Skin temperature sensor

The skin temperature sensor is a NTC.

In addition to the recognition "sensor plugged in" a short-circuiting link is installed in the plug (not used with software version 11.n and 21.n).

T (°C)	R (Ohm)
33.0	1588.3
36.0	1411.3
38.0	1293.3